

CVision: A Navigator for the Visually Impaired

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What is CVision?

CVision is a deep learning based Python program designed to assist the visually-impaired in navigating their surroundings.

Real-time video from a portable camera is processed to generate directional sound cues to be heard on headphones. These sounds reflect the relative locations and distances of detected objects.

Potential dangers such as very close objects are alerted to the user.

System

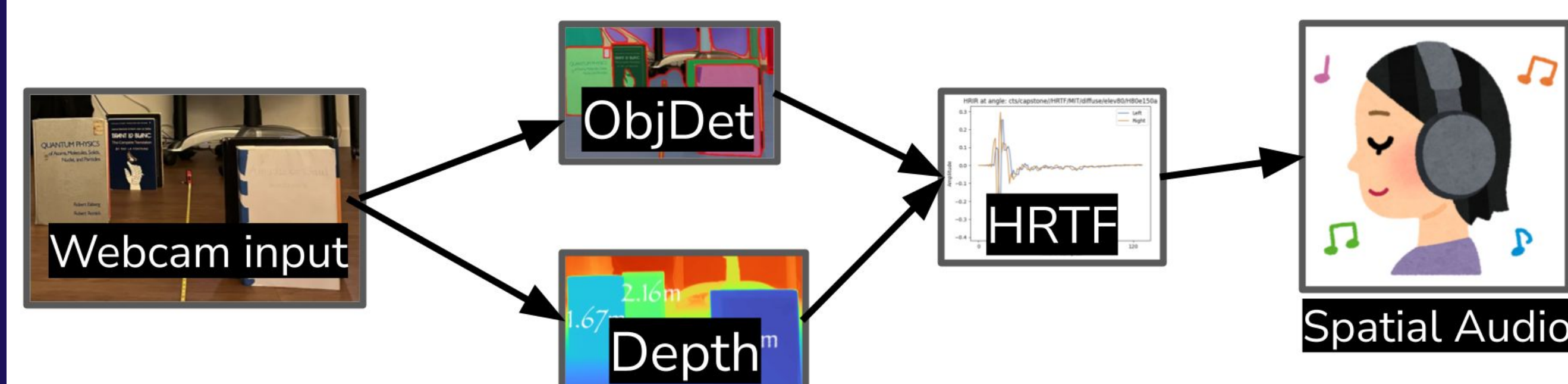


Fig 1. CVision data flow diagram

Our system captures real-time images and applies object detection in conjunction with depth mapping.

It uses head-related transfer functions (HRTFs) to generate spatial audio cues, enabling users to perceive the relative location of surrounding objects.

Modes of operation

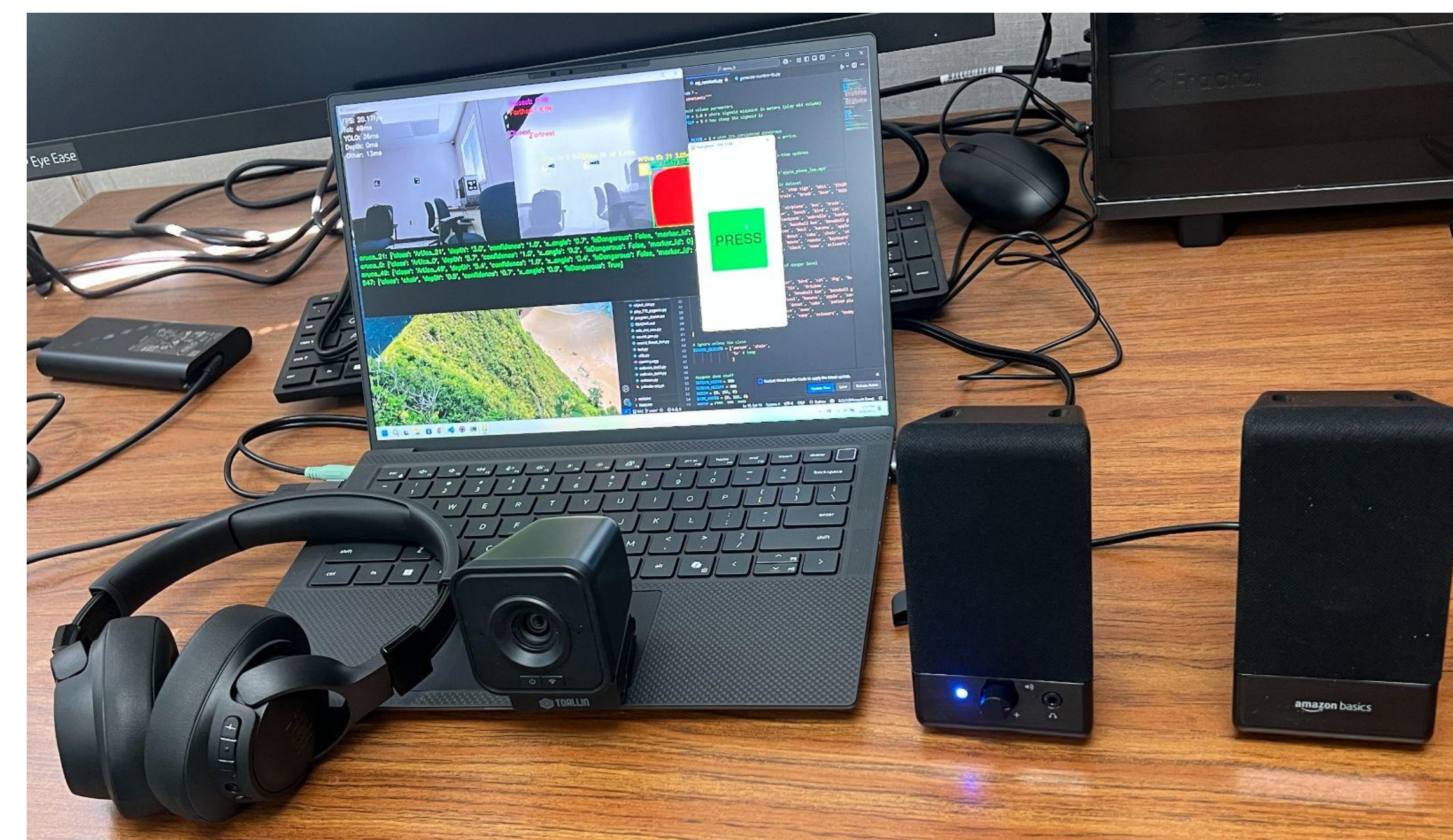


Fig 2. Uses GPU computer, webcam, and headphones (speakers for demo)

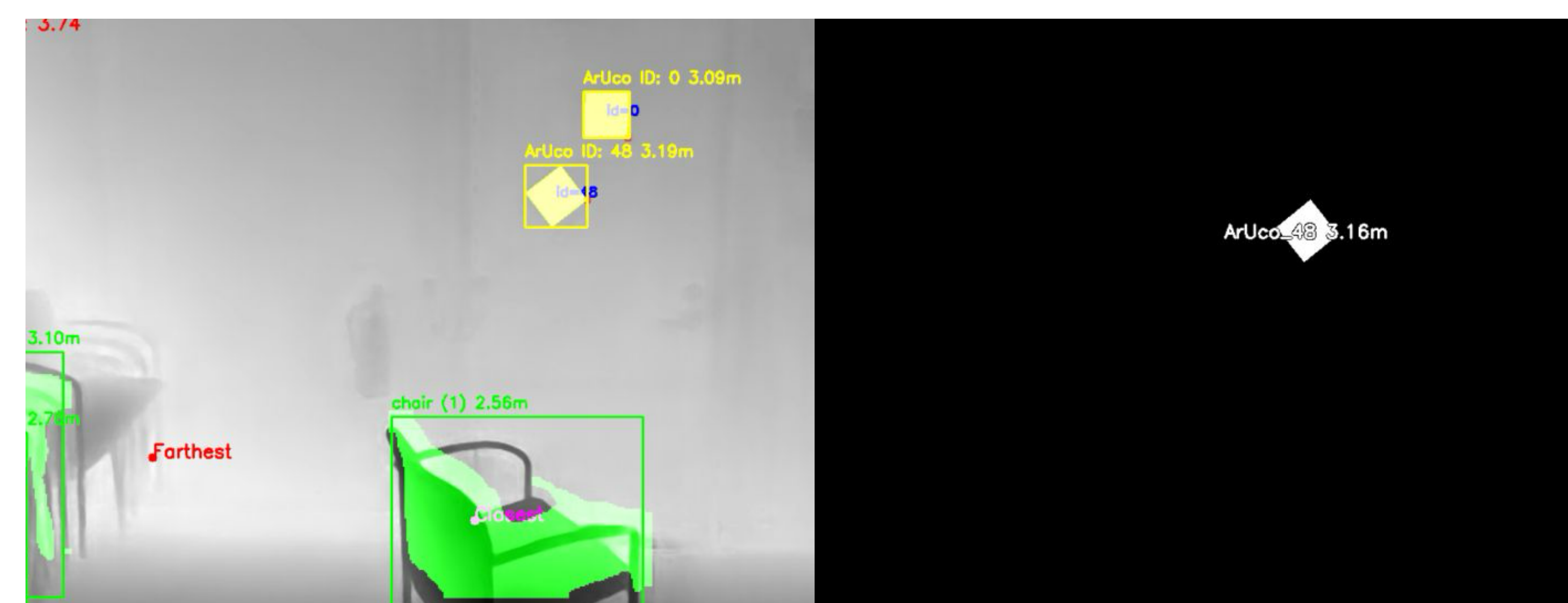


Fig 3. Tracking a specific object

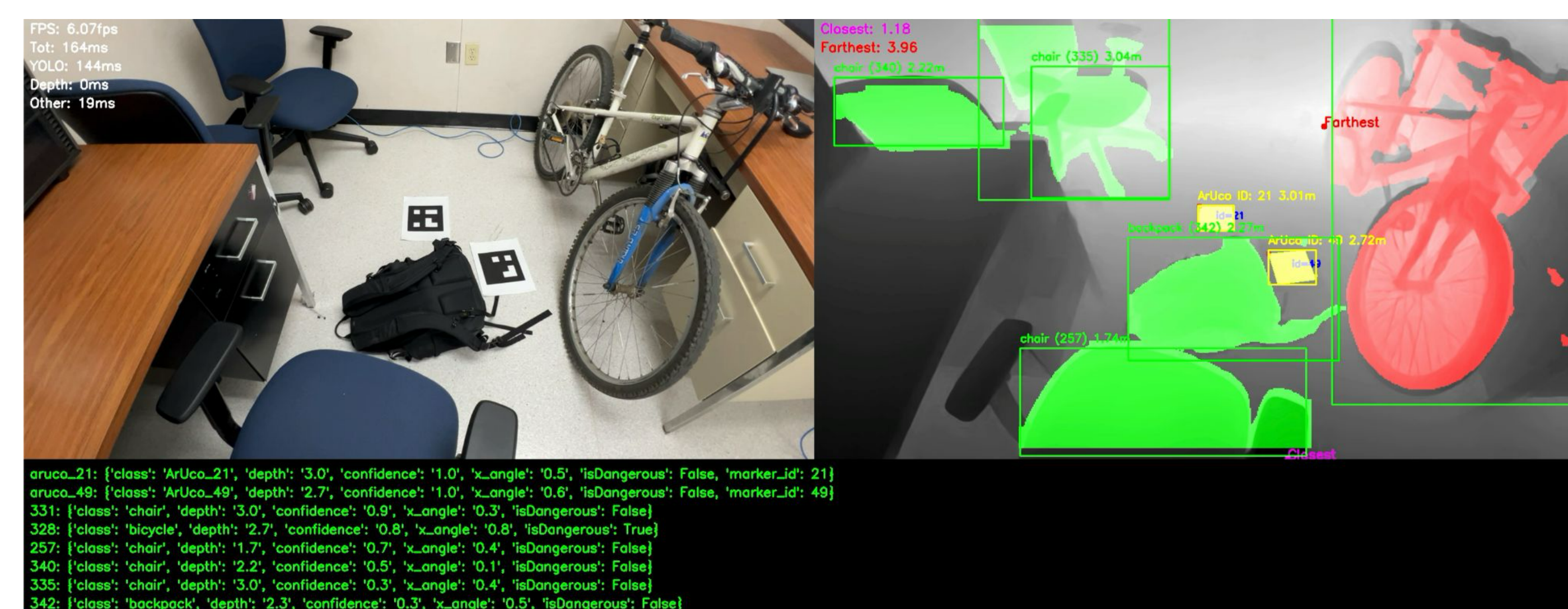


Fig 4. Showing normal, danger, and ArUco detections

Monocular depth Maps

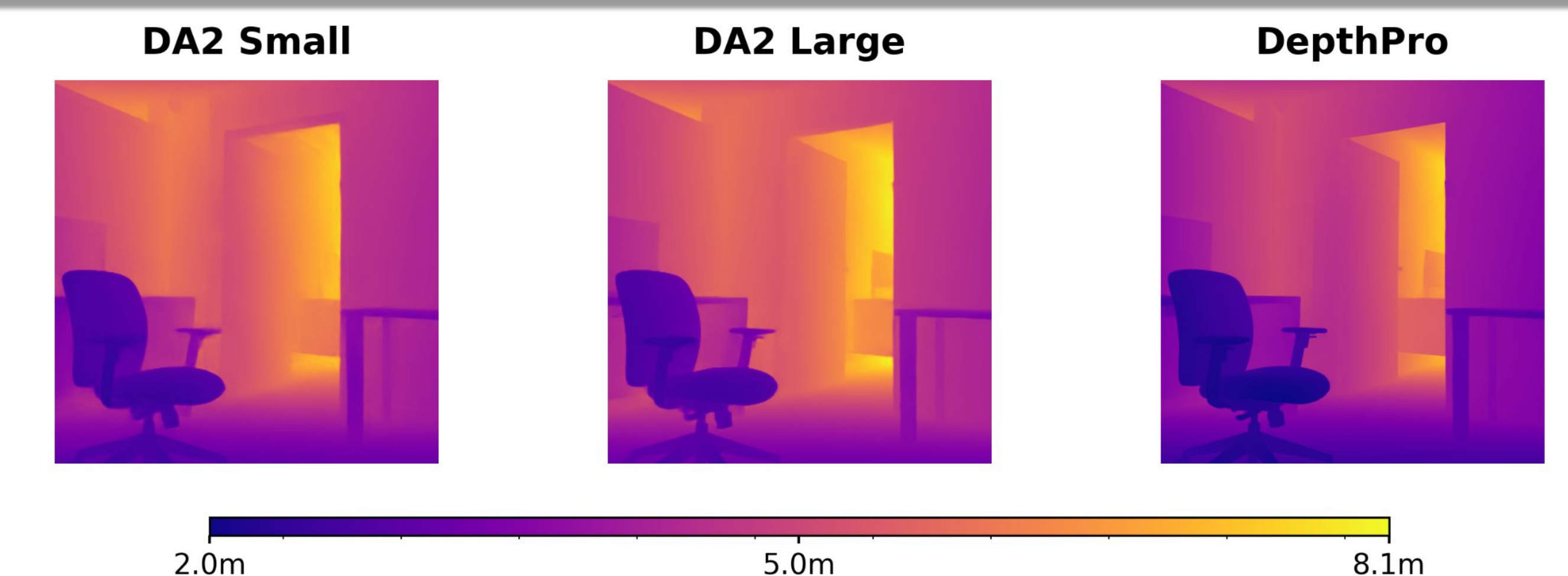


Fig 5. Monocular depth maps models (depth from one camera only) are the main bottleneck. Tried multithreading, frame skipping, low-res input, and smaller models. Used metric DepthAnything v2 small (DA2 small) in demo for speed.

Object Detection

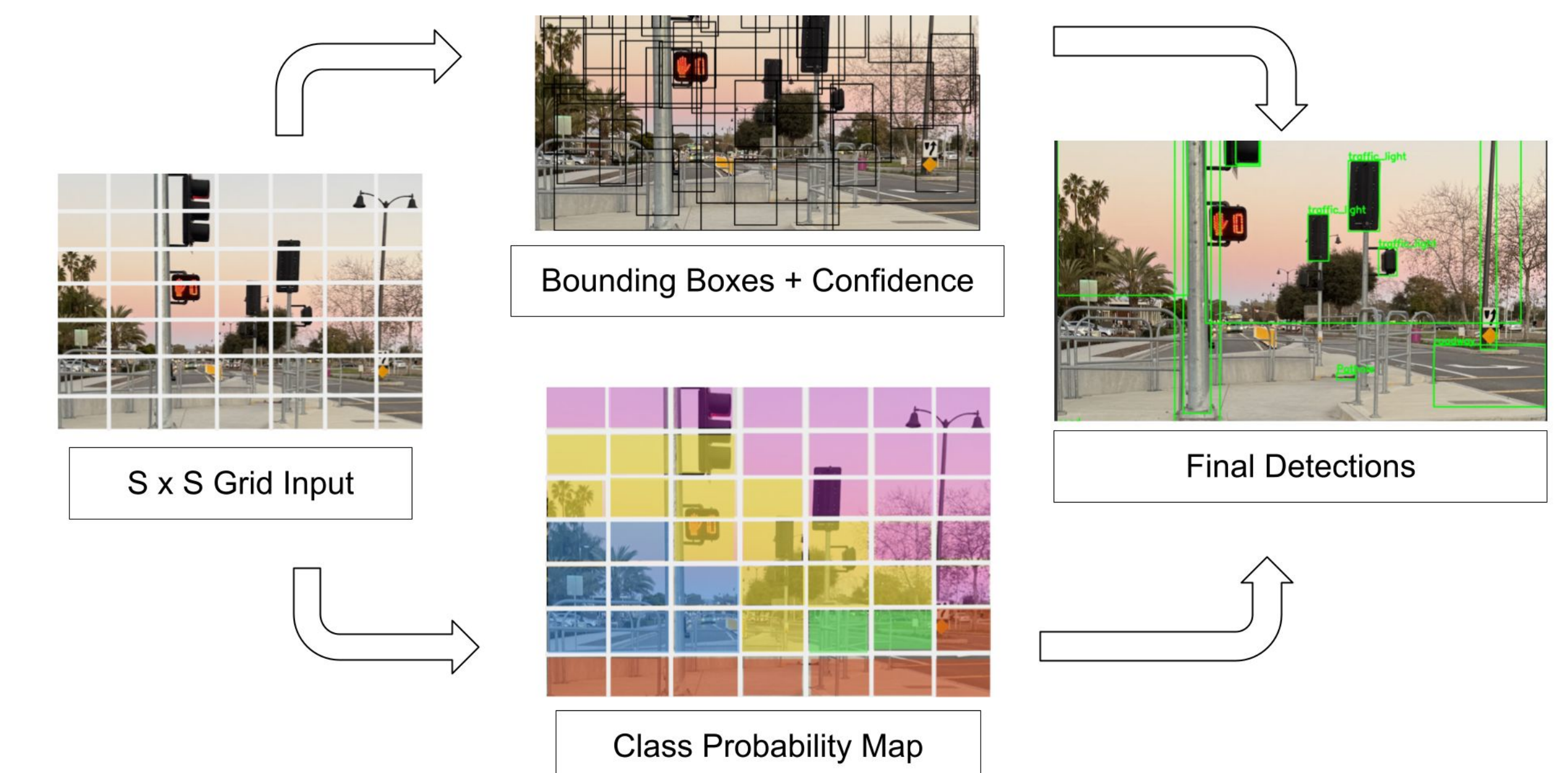


Fig 6. YOLO object detection. Used YOLOv8 for speed. Also trained fine-tuned version using a sidewalk dataset.

Head related Transfer Function (HRTF)

- Microphone in right and left ears.
- Play a sound in each speaker, one at a time, to measure transfer functions using right and left mics.
- Used HRTFs measured by MIT media lab in 1994.

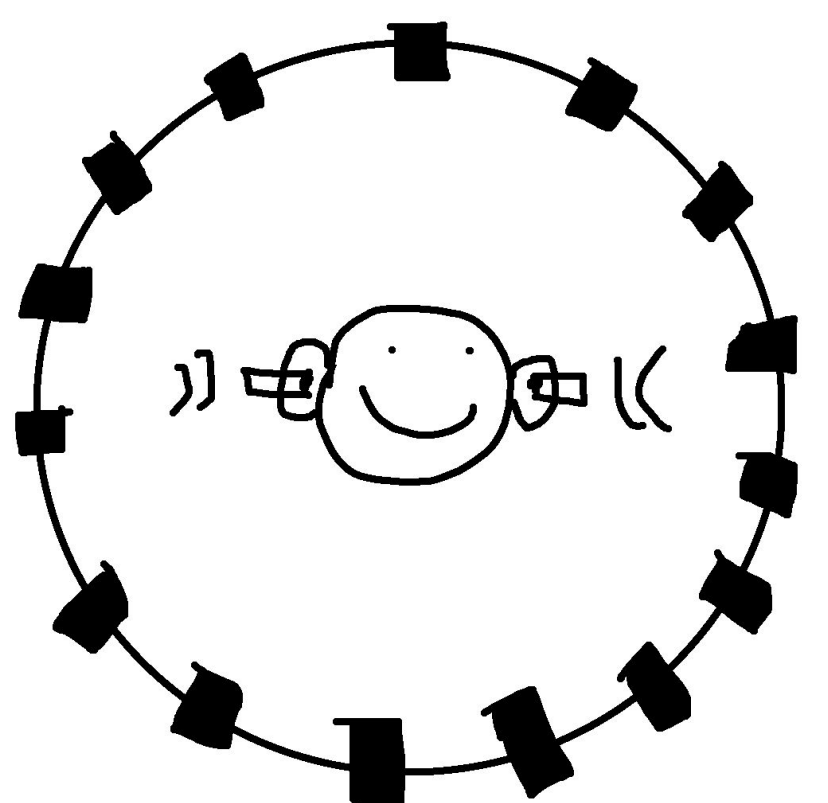


Fig 7. HRTF measurement. Black boxes are speakers. Two mics in human ear models.

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